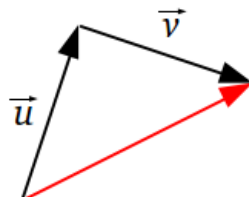


### Vector Basics

J. Garvin



### Vectors vs. Scalars

A *vector* is a quantity with both *magnitude* and *direction*.

A *scalar* is a quantity that has only *magnitude*.

For example, speed is a scalar (80 km/h), while velocity is a vector (75 km/h NE).

### Vectors vs. Scalars

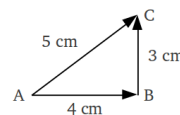
#### Example

Classify each quantity as a vector or a scalar.

- 1 The temperature outside is 3°C (scalar)
- 2 Gravity causes a ball to accelerate at 9.8 m/s<sup>2</sup> downward (vector)
- 3 A student has a mass of 68 kg (scalar)
- 4 A car drives 25 km west (vector)

### Vector Notation

Vectors are often represented using arrows, since arrows have both a length (magnitude) and a direction.



The three vectors are  $\vec{AB}$ ,  $\vec{BC}$  and  $\vec{AC}$ .

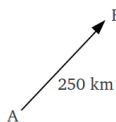
The magnitude of a vector is usually indicated using vertical bars (absolute value).

$$|\vec{AB}| = 4 \quad |\vec{BC}| = 3 \quad |\vec{AC}| = 5$$

### Representing Vectors

Vectors can be represented in many ways.

- 1 Using a diagram



- 2 Using words (250 km northeast)
- 3 Using symbols ( $\vec{AB}$ )

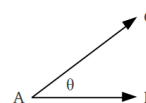
### Terminology

*Equivalent vectors* are those with the same magnitude and direction (e.g. 9.8 m/s<sup>2</sup> down and 9.8 m/s<sup>2</sup> down).

*Opposite vectors* are those with the same magnitude, but have the opposite direction (e.g. 5 km NE and 5 km SW). The vector  $-\vec{v}$  is opposite to  $\vec{v}$ .

*Parallel vectors* may have different magnitudes, but their directions are either the same or opposite (e.g. 3 N left, 15 N right).

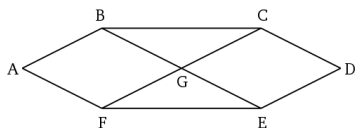
The *angle between two vectors*,  $\theta$ , is the acute or obtuse angle formed between them when drawn tail-to-tail.



### Terminology

#### Example

For  $\vec{AB}$  below, state two equivalent vectors, two opposite vectors, and two parallel vectors.



Equivalent:  $\vec{FG}$ ,  $\vec{GC}$  and  $\vec{ED}$ .

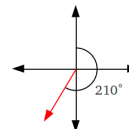
Opposite:  $\vec{CG}$ ,  $\vec{GF}$ ,  $\vec{DE}$  and  $\vec{BA}$ .

Parallel: all seven above, plus  $\vec{FC}$  and  $\vec{CE}$ .

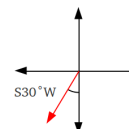
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### Bearings

True bearings rotate clockwise, beginning at the north.



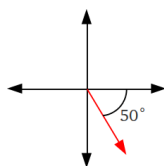
Quadrant bearings measure the angle east or west of the north-south line.



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### Bearings

Express the following vector using both a true bearing and quadrant bearing.



The true bearing is  $140^\circ$ , and the quadrant bearing is  $S40^\circ E$ .

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### Unit Vectors

A unit vector,  $\hat{v}$ , is a vector with a magnitude of 1. That is,  $|\hat{v}| = 1$ .

Since  $k \cdot \frac{1}{k} = 1$ , a unit vector in the direction of any vector  $\vec{v}$  can be found by multiplying  $\vec{v}$  by the reciprocal of its magnitude.

$$\hat{v} = \frac{1}{|\vec{v}|} \cdot \vec{v} \text{ or } \hat{v} = \frac{\vec{v}}{|\vec{v}|}$$

Any vector,  $\vec{v}$ , can be expressed as the product of its magnitude,  $|\vec{v}|$  and a unit vector,  $\hat{v}$ .

$$\vec{v} = \hat{v} \cdot |\vec{v}|$$

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### Unit Vectors

#### Example

Vector  $\vec{v}$  has a magnitude of  $\frac{5}{2}$  units, with a bearing of  $35^\circ$ . Determine two unit vectors parallel to  $\vec{v}$ .

Since  $\frac{5}{2} \cdot \frac{2}{5} = 1$ , vector  $\vec{a} = \frac{2}{5}\vec{v}$  is a unit vector parallel to  $\vec{v}$ .

Since  $-\vec{v}$  is parallel to  $\vec{v}$ ,  $\vec{b} = -\frac{2}{5}\vec{v}$  is another unit vector parallel to  $\vec{v}$ .

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### Questions?



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